

DIFFERENT TEXTURE CLASSIFICATION AND AGE PREDICTION OF FACE IMAGES USING PEANOCOUNT DECISION CLASSIFIER

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ABSTRACT

Recognition of skin is used in many applications ranging from algorithms for predicting age , face detection, gender classification, and to objectionable image filtering. These data collections are growing rapidly and can therefore be considered as spatial data streams. Time is a major issue for data stream classification. However, these spatial data sets are too large to be classified effectively in a reasonable amount of time using existing methods. In this work a novel and computational fast algorithm is proposed for predicting age of humans with PeanoCountTree (P-Tree). The predicting system was developed and tested based on texture features extracted local gradient patterns (LGP) and gray level co-occurrence matrix (GLCM) to give better and more predicting accuracy with a range of time period. The P-Tree is a spatial data organization that provides a lossless compressed representation of a spatial data set and facilitates efficient classification and other data mining techniques. Using P-tree structure, fast calculation of measurements, such as information gain, can be achieved. We compare P-tree decision tree induction classification and a classical decision tree induction method with respect to the speed at which the classifier can be built (and rebuilt when substantial amounts of new data arrive). Experimental results show that the P-tree method is significantly faster than existing classification methods, making it the preferred method for mining on spatial data streams.

Key words: Feature extraction, Gradient Operator, GLCM, P-Classifer, bSQ, Peano Count Tree, Mining.

INTRODUCTION

Recognition of human skin is an important task for both computer vision and graphics. For computer vision, accurate recognition of skin texture can greatly assist algorithms for human face recognition or facial feature tracking. In computer graphics, facial animation is an important problem which necessitates reliable skin texture recognition. In addition to computer vision and graphics, skin recognition is useful in dermatology and several industrial fields. In dermatology, the skin recognition can be used to develop methods for computer-assisted diagnosis of Skin disorders, while in the pharmaceutical industry; quantification is useful when applied to measuring healing Progress. Many skin segmentation methods depend on skin color [1] [2] which has many difficulties. For the above reasons combining the texture features of

skin with its color feature will increase the accuracy of skin recognition. Skin is a complex landscape that is difficult to model for many reasons. The skin texture features depends on many variables such as body location (knuckle vs. torso), subject parameters (age/gender/health) and imaging parameters (lighting and camera). Also as with many real world surfaces, skin appearance is strongly affected by the age with folds on the face as shown in the below figure1.



Figure 1: Skin texture difference with age.

In many areas, large quantities of data are generated and collected every day, such as international airports, security surveillance systems, and Verification and authentication in different places. These data arrive too fast to be analyzed or mined in time. Such kinds of data are called “data streams” [3]. Classifying open-ended data streams brings challenges and opportunities since traditional techniques often cannot complete the work as quickly as the data is arriving in the stream [4]. Such data sets can be very large and are often archived in deep storage before valuable information can be obtained from them. An objective of spatial data stream mining is to mine such data in near real time prior to deep storage archiving. Classification is one of the important areas of data mining. In classification task, a training set (or called learning set) is identified for the construction of a classifier. Each record in the learning set has several attributes, one of which, the goal or class label attribute, indicates the class to which each record belongs. The classifier, once built and tested, is used to predict the class label of new records that do not yet have a class label attribute value. A test set is used to test the accuracy of the classifier. The classifier, once certified, is used to predict the class label of future unclassified data. Different models have been proposed for classification such as decision trees, neural networks, Bayesian belief networks, fuzzy sets, and generic models. Among these models, decision trees are widely used for classification. We focus on decision tree induction in this paper. ID3 (and its variants such as C4.5) [5, 6] and CART [7] are among the best known classifiers that use decision trees. Other decision tree classifiers include Interval Classifier [8] and SPRINT [9] which concentrate on making it possible to mine databases that do not fit in main memory by only requiring sequential scans of the data. Classification has been applied in many fields, such as retail target marketing, customer retention, fraud detection and medical diagnosis. Spatial data is a promising area for classification. In this paper, we propose a decision tree based model to perform classification on spatial data streams. A new data structure, the Peano Count Tree (P-tree) [10] is used to build the decision tree classifier. P-trees represent spatial data bit-by-bit in a recursive quadrant-by-quadrant arrangement. With the information in P-trees, we can rapidly build the decision tree. Each new component in a spatial data stream is converted to P-trees and then added to the training set as soon

as possible. Typically, a window of data components from the stream is used to build (or rebuild) the classifier. There are many ways to define the window, depending on the data and application.

In this paper, the focus is on feature extraction and building fast classifier algorithm. The rest of the paper is organized as follows. In section 2, gives related work done in these areas of research called literature survey. In section 3 explains features extraction using gradient and Gray Level Co-occurrence Matrix (GLCM) region is extracted. In section 4, we briefly introduce the data formats of spatial data and describe the P-tree data structure and algebra. In Section 5, we detail our experimental results with an example using decision tree induction classifier. Finally, there is a conclusion in Section 6.

2. LITERATURE SURVEY

Most existing skin segmentation techniques involve the Classification of individual image pixels into skin and non-skin categories on the basis of pixel color. Lots of relative studies of skin color pixel classification have been reported. In [11] Nidhal K. Al Abbadi proposed a method for skin texture recognition using neural network. They proposed a skin recognition system. This system is using skin color feature and texture feature. In [12] authors proposed a texture recognition system based on Grey Level Co-occurrence Matrix (GLCM) for automatic recognizing the texture. Based on the differences in texture appearance skin texture is categorized into 3 different disease classes. Features extracted from GLCM are contrast, homogeneity, mean and variance. Based on the differences in texture appearance skin texture is categorized into 3 different disease classes. Brand and Mason [13] compared three different techniques on the Compaq database: thresholding the red-green ratio, color space mapping with 1D pointer and RGB skin probability map. In [14] authors implemented a classifier using MLP neural network for face detection. Face can be detected through different features similar to shape skin texture and skin color. They are interested by the design of ANN not by the features. In [15] authors proposed a technique for image segmentation using texture content. Texture features are extracted from spatial blocks using quad tree decomposition. All feature sets are computed from Quadrature Mirror Filter (QMF) wavelet representation. Texture feature extraction can be done based on block-based features, wavelet sub band features. Numbers of comparative studies of skin color pixel classification have been reported. LDP is a general framework to encode directional pattern features based on local derivative variations [16]. The n^{th} -order LDP is proposed to encode the $(n-1)^{\text{th}}$ -order local derivative direction variations, which can capture more detailed information than the first-order local pattern used in local binary pattern (LBP). Different from LBP encoding the relationship between the central point and its neighbors, the LDP templates extract high-order local information by encoding various distinctive spatial relationships contained in a given local region.

3. OBJECTIVES

1. To design a computational fast age predicting algorithm using face texture features.
2. To classify the face image into range of age groups using Peano count trees an image mining concept.

3. To extract texture feature like local gradient patterns and gray level co-occurrence.

4. METHODOLOGY

The methodology includes as follows:

1. Select an Input Image.
2. Detect skin area in Input Image
3. Detect Features.
4. Save Face into Database with its record, class label, attributes, and age.
5. Design a learning data set for more images.
7. The values are converted into bSQ file format.
8. Spatial data organization using Peano count tree.
9. Decision Tree is constructed using ID3 method to classify the data.
10. Using the Classified data test image age is predicted.

Here we want to use some rules and assumptions which are available in bio-informatics to predict the age. There are so many assumptions in Bio information which are giving accurate results in prediction of age. In detail methodology is discussed in next section.

5. FEATURE EXTRACTION

A. Local gradient patterns

To investigate the feasibility and effectiveness of using high-order local patterns for face representation. An Local gradient patterns is proposed, in which the first-order derivative direction variations based on a binary coding function. In this scheme, LBP is conceptually regarded as the nondirectional first-order local pattern operator, because LBP encodes all-direction first-order derivative binary result while LDP encodes the higher-order derivative information which contains more detailed discriminative features that the first-order local pattern (LBP) can not obtain from an image. Given an image $I(Z)$, we calculate first-order derivatives along 0° , 45° , 90° and 135° directions, which is denoted as $I'_\alpha(Z)$ where $\alpha = 0^\circ, 45^\circ, 90^\circ$ and 135° .

$$(a) I'_{0^\circ}(Z_0) = I(Z_0) - I(Z_4)$$

$$(b) I'_{45^\circ}(Z_0) = I(Z_0) - I(Z_3)$$

$$(c) I'_{90^\circ}(Z_0) = I(Z_0) - I(Z_2)$$

$$(d) I'_{135^\circ}(Z_0) = I(Z_0) - I(Z_1)$$

If Z_0 is one point in $I(Z)$, neighboring point around Z_0 (see Fig. 2). So the four first-order derivatives at $Z=Z_0$ are

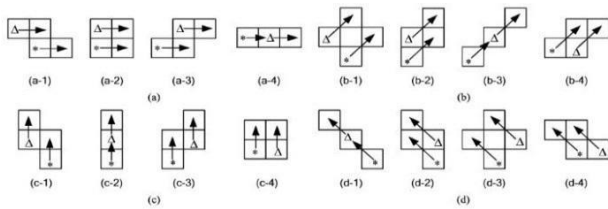


Figure 2 Gradient operator (a) 0^0 (b) 45^0 (c) 90^0 (d) 135^0

Once the first order gradient details of the image is obtained. The energy of the local gradient patterns is computed from the LDP image by the following equation.

$$Energy = \sum_{i,j}^{M,N} LDP(i,j)^2 \tag{1}$$

B.Gray Level Co-occurrence Matrix (GLCM)

Texture analysis has been an active area of research in pattern recognition. A variety of techniques have been used for measuring textural similarity. In 1973, Haralick et al. proposed co-occurrence matrix (GLCM) representation of texture features to mathematically represent gray level spatial dependence of texture in an image [17]. In this method the co-occurrence matrix is constructed based on the orientation and distance between image pixels. Meaningful statistics are extracted from this co-occurrence matrix, as the representation of texture. Since basic texture patterns are governed by periodic occurrence of certain gray levels, co-occurrence of gray levels at predefined relative positions can be a reasonable measure of the presence of texture and periodicity of the patterns. Several texture features such as entropy, energy, contrast, and homogeneity, can be extracted from the co-occurrence matrix of gray levels of an image. The gray level co-occurrence matrix $C(i, j)$ is defined by first specifying a displacement vector $dx, y = (\delta x, \delta y)$ (where $\delta x, \delta y$ are the displacements in the x and y directions respectively) and then counting all pairs of Pixels separated by displacement dx, y and having gray levels i and j . The matrix $C(i, j)$ is normalized by dividing each element in the matrix by the total number of pixel pairs. Using this co-occurrence matrix, the texture features Metrics are computed as follows.

$$Entropy = \sum_{i,j}^{M,N} C(i,j) \log(C(i,j)) \tag{2}$$

$$Contrast = \sum_{i,j}^{M,N} (i - j)^2 C(i,j) \tag{3}$$

$$Homogeneity = \sum_{i,j}^{M,N} \frac{C(i,j)}{1 + |i - j|} \tag{4}$$

C.Feature dataset Organization using PeanoCount Tree

All the values have been scaled to values between 0 and 255 for simplicity. The pixel coordinates in raster order constitute the key attribute. One can view such data as table in relational form where each pixel is a tuple and each band is an attribute. There are several formats used for spatial data, such as Band Sequential (BSQ), Band Interleaved by Line (BIL) and Band Interleaved by Pixel (BIP). The new format which was called as bit Sequential Organization (bSQ) is introduced. Since each intensity value ranges from 0 to 255, which can be represented as a byte, we try to split each bit in one band into a separate file, called a bSQ file. For example, for a TIFF image with three bands, we have 24bSQ files.

This example has been taken from [18]. The following relation table contains 4 features of 4-bit data values.

Record	B1	B2	B3	B4
0	0011	0111	1000	1011
1	0011	0011	1000	1111
2	0111	0011	0100	1011
3	0111	0010	0101	1011

4	0011	0111	1000	1011
5	0011	0011	1000	1011
6	0111	0011	0100	1011
7	0111	0010	0101	1011

8	0010	1011	1000	1111
9	0010	1011	1000	1111
10	1010	1010	0100	1011
11	1111	1010	0100	1011

12	0010	1011	1000	1111
13	1010	1011	1000	1111
14	1111	1010	0100	1011
15	1111	1010	0100	1011

Table 1 : Feature sets in relational table

This dataset is converted in bSQ format. The feature-1bit-bands would be like below if we display the bSQformat in 2- dimension

B11	B12	B13	B14
0000	0011	1111	1111
0000	0011	1111	1111
0011	0001	1111	0001
0111	0011	1111	0011

There is a constraint on bSQ formation. P-tree requires the number of rows and columns in bSQ file be multiple of four. In case, the number of tuples in database is not a multiple of four we need to pad zero vectors at the end; so that it is.

Based on this idea, to identify a person, the recognition system works as follows:

- Basic p-trees of the enrolled feature sets are constructed as preprocessing. This is a one-time job.
- Feature vector of the person to be recognized is extracted.
- A tuple p-tree of this feature vector is generated based on the basic p-trees.
- If the root count of this tuple p-tree are classified by Peano-Tree classifier.

These tuple p-tree values are subjected through decision tree will different age groups will have different gradient energy.

D. P-Tree based Decision Classifier

Classification is a data mining technique that typically involves three phases, a learning phase, a testing phase and an application phase. A learning model or classifier is built during the learning phase. It may be in the form of classification rules, a decision tree, or a mathematical formula. Since the class label of each training sample is provided, this approach is known as supervised learning. In unsupervised learning (clustering), the class labels are not known in advance. In the testing phase test data are used to assess the accuracy of classifier. If the classifier passes the test phase, it is used for the classification of new, unclassified data tuples. This is the application phase. The classifier *predicts* the class label for these new data samples. In this paper, we consider the classification of spatial data in which the resulting classifier is a decision tree (decision tree induction). Our contributions include

- (1) A set of classification-ready data structures called Peano Count trees, which are compact, rich in information and facilitate classification;
- (2) A data structure for organizing the inputs to decision tree induction, the Peano count cube.
- (3) A fast decision tree induction algorithm, which employs these structures. We point out the classifier is precisely the classifier built by the ID3 decision tree induction algorithm.

The point of the work is to reduce the time it takes to build and rebuild the classifier as new data continue to arrive. This is very important for performing classification on data streams.

A Decision Tree is a flowchart-like structure in which each node denotes a test on an attribute. Each branch represents an outcome of the test and the leaf nodes represent class's or class distributions. Unknown samples can be classified by testing attributes against the tree. The path traced from root to leaf holds the class prediction for that sample. The basic algorithm for inducing a decision tree from the learning or training sample set is as follows [19]:

- Initially the decision tree is a single node representing the entire training set.
- If all samples are in the same class, this node becomes a leaf and is labeled with that class label.
- Otherwise, an entropy-based measure, "information gain", is used as a heuristic for selecting the attribute which best separates the samples into individual classes (the "decision" attribute).
- A branch is created for each value of the test attribute and samples are partitioned accordingly.
- The algorithm advances recursively to form the decision tree for the sub-sample set at each partition. Once an attribute has been used, it is not considered in descendent nodes.
- The algorithm stops when all samples for a given node belong to the same class or when there are no remaining attributes (or some other stopping condition)

The attribute selected at each decision tree level is the one with the highest information gain. The information gain of an attribute is computed by using the following algorithm. Assume $B[0]$ is the class attribute; the others are non-class attributes. We store the decision path for each node. For example, in the decision tree below (Figure 3), the decision path for node N_{09} is "Band2, value 0011, Band3, value 1000". We use RC to denote the root count of a P-tree, given node N 's decision path $B[1], V[1], B[2], V[2], \dots, B[t], V[t]$, let P-tree $P = P_{B[1],V[1]} \wedge P_{B[2],V[2]} \wedge \dots \wedge P_{B[t],V[t]}$, we can calculate node N 's information $I(P)$ through

$$I(p) = - \sum_{i=1}^n p(i) \log_2(p(i))$$

Where $p_i = \frac{RC(P \wedge P_{B[0], V_0[i]})}{RC(P)}$, here $V_0[1]..V_0[n]$ are possible $B[0]$ values if classified by $B[0]$ at node N . If N is the root node, then P is the full P-tree (root count is the total number of transactions). Now if we want to evaluate the information gain of attribute A at node N , we can use the formula: $\text{Gain}(A) = I(P) - E(A)$, where entropy

$$E(A) = \sum_{i=1}^n I(P \wedge P_{A, VA[i]}) * \frac{RC(P \wedge P_{A, VA[i]})}{RC(P)}$$

Where $VA[1], VA[n]$ are possible A values if classified by attribute A at

Thus, the B1 basic P-trees are as follows (tree pointers are omitted).

P1, 1P1, 2 P1, 3P1, 4

5 7 16 11

0014 0403 4403

0001 0111 0111

Then we generate basic P-trees and value P-trees similarly to F2, F3 and F4. Start with A = F2. Because the node currently dealing is the root node, P is the full P-tree. So pi can be 3/16, 1/4, 1/4, 1/8, 3/16, thus we can calculate

$$I(P) = 3/16 * \log_2(3/16) + 4/16 * \log_2(4/16) + 4/16 * \log_2(4/16) + 2/16 * \log_2(2/16) + 3/16 * \log_2(3/16)$$

$$I(P) = 2.281$$

To calculate E (B2), first P^APA, VA[i] should be all the value P-trees of B2. Then I (P^APA, VA[i]) can be calculated by ANDing all the B2 value P-trees and B1 value P-trees. Finally we get E (B2) = 0.656 and Gain (B2) = 1.625. Likewise, the Gains of B3 and B4 are computed: Gain (B3) = 1.084, Gain (B4) = 0.568. Thus, B2 is selected as the first level decision attribute. Branches are created for each value of F2 and samples are partitioned accordingly.

B2=0010 → Sample_Set_1

B2=0011 → Sample_Set_2

B2=0111 → Sample_Set_3

B2=1010 → Sample_Set_4

B2=1011 → Sample_Set_5

Advancing the algorithm recursively to each subsample set, it is unnecessary to rescan the learning set to form these sub-sample sets, since the P-trees for those samples have been computed. The algorithm will terminate with the decision tree:

B2=0010 → B1=0111

B2=0011 → B3=0100 → B1=0111

→ B3=1000 → B1=0011

B2=0111 → B1=0011

B2=1010 → B1=1111

B2=1011 → B1=0010

Based on the above describe entropy and gain values root nodes are selected. The feature in this above example F2 is having more gain when compare with F3 and F4. So F2 is root node and the decision will process for next step recursively until all values pass for the testing to reach leaf node. The branch will give the path of particular tuple in the data set with class label as shown in the following decision tree.

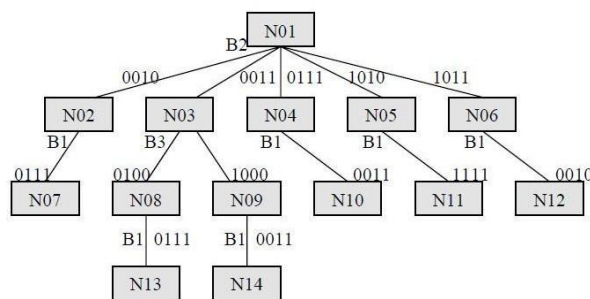


Figure 3 Decision Tree on example dataset

6. EXPERIMENTAL RESULTS

A spatial image can be viewed as a 2-dimensional array of pixels. Associated with each person to computed energy of local gradient pattern image and Gray level Co-occurrence metric (GLCM) from the data base. The energy of LGP is taken as class label and global texture features as various descriptive attributes, called “features”. Based on idea of texture analysis, it is understood with the increase age of particular person the wrinkles on the face will appear. Which change the properties of skin texture in terms of more number of changes will happen. This can be identified through first gradient operators as shown below figure 2. This energy of the gradient image is used as a class label for further processing and using intensity based feature of GLCM like *Entropy, Contrast and homogeneity*.

Finally, prediction: the minimum Euclidean distance of the Testing feature vector from the average distance of the Training feature vectors was computed. The class with the minimum distance was defined as the age result. Thus the image was labeled with the age group of that particular class. The performance of age prediction is the age range and not the exact age of the human face.

In this example the data is collected from different age groups of face data base. The extracted features from each person in training dataset are used as attributes and class label. The goal is to classify the data using GLCM features as the class label attribute and then to use the resulting classifier to predict the age group of particular face recognition. Branches are created for each value of the selected attribute and subsets are partitioned accordingly.

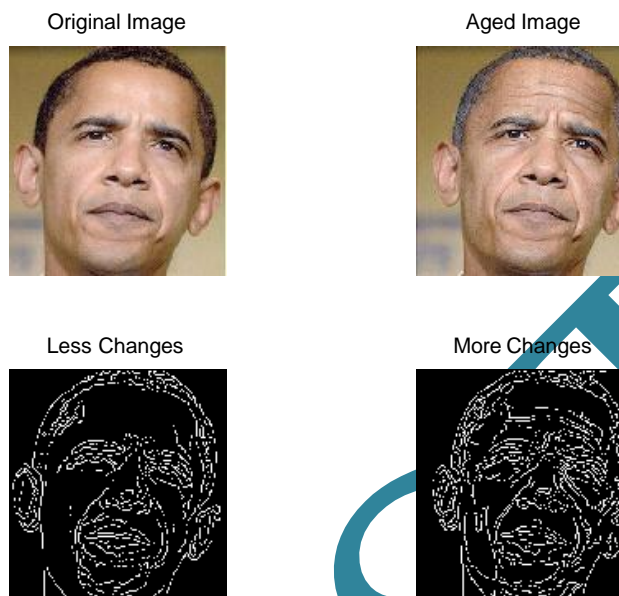


Figure 4 Gradient Images with respect to Age

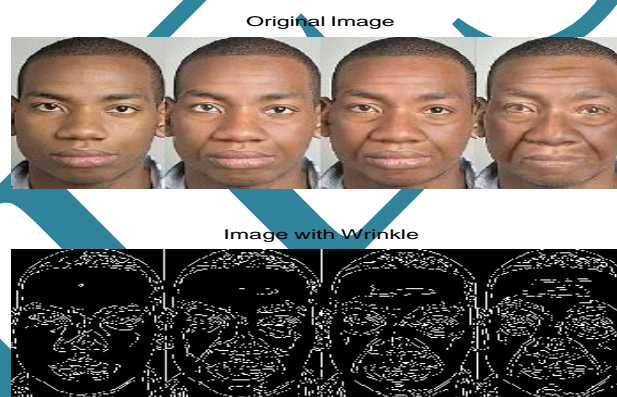


Figure 5 Gradient Images with respect to different Ages

The following training set contains 4 bands of 4-bit data values (expressed in decimal and binary). F1 stands for GCLM feature. F2, F3, and F4 stand for the other feature like *Entropy*, *Contrast* and *homogeneity*.

To predict the age of the person using decision tree, the recognition system works as follows: 1) Basic p-trees of the enrolled feature sets are constructed as preprocessing. This is a one-time job. 2) Feature vector of the person to be recognized is extracted. 3) A tuple p-tree of this feature vector is generated based on the basic p-trees. 4) If the root count of this tuple p-tree is more than zero, then we have one or more matches. The Indexes of those matched tuples at the relational database can be figured out using decision tree. This is a

nice way of feature matching, as it doesn't need to scan the database at all. A few algebraic operations perform the job. Besides, the AND operation which produce the tuple p-trees is fast [20] Thus, we have framework for real-time recognition system. We use the whole data set for mining so as to get as better accuracy as we can. This data are divided into learning and test data sets

7. RECOMMENDATIONS

Now a day's face identification has vital importance in so many business alliances. This work is now only applied for face recognition but to show more effectively this can be enhanced for video mining. This can also be enhanced for classification of satellite images to identify land area, green area and water area based on satellite images and may to predict weather conditions in various seasons. Even it can also be used to identify skin diseases.

8. CONCLUSION

This Paper shows the Gradient Texture Classification based on Age Prediction of Face Images using PeanoCount Decision Classifier. In this a novel and computational fast algorithm is proposed for predicting age of humans with PeanoCount Tree (P-Tree). The predicting system was developed and tested based on texture features extracted local gradient patterns (LGP) and gray level co-occurrence matrix (GLMC) to give better and more predicting accuracy with a range of time period. Experimental results show that the P-tree method is significantly faster than existing classification methods.

The proposed system is used to design an automated system which is more interested area for recognizing different changes that occur with age. This system is based on texture analysis. Here first order gradient operator and GLCM is taken as a method of feature extraction. For analyzing texture, symmetrical normalized GLCM is computed along four directions. From this matrix texture features are calculated and averaged over 4 directions. The gradient energy is calculated along with contrast, homogeneity and entropy. These features are very useful to recognize texture of skin and these features are classified with a novel P-tree classifier. This classifier uses decision tree induction that is especially useful for the classification of spatial data streams. We use the data organization, bit Sequential organization (bSQ) and a lossless, data-mining ready data structure, the Peano Count Tree (P-tree), to represent the information needed for classification in an efficient and ready-to-use form. This makes classification of open-ended streaming datasets feasible in near real time. We have tested the system with plenty of images which is showing correct results as per expectations.

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